



DeCAIR Course Syllabus Form

Author(s)	Eyad Almaita			
Organization Name(s)	Tafila technical University			
WP Number & Title	Work Package 2: Development of new MSc and BSc programs in AIR			
Activity Number & Title	Activity 2.2: Designing and developing syllabi and content for the agreed upon courses in the new programs			
WP Leader	Francesco Masulli, University of Genoa			
Due Date of Delivery	1/2/2022	Project Month	M14	
Submission Date	5/11/2021	Project Month	M11	

Revision History

Version	Date	Author	Description	Action *	Page(s)
1	5/11/2021	Eyad Almaita	Original (base) document	С	1-6
2	13/12/2021	TTU Team	Revision	U	2-4
3	31/01/2022	Eyad Almaita	Revison	U	2-6
4					

^(*) Action: C = Creation, I = Insert, U = Update, R = Replace, D = Delete

Disclaimer

This project has been co-funded by the Erasmus+ Programme of the European Union.

You are free to share, copy and redistribute the material in any medium or format, as well as adapt, transform, and build upon the material for any purpose, even commercially, provided that you give appropriate credit to the project and the partnership, and indicate if any changes were made. You may do so in any reasonable manner, but not in any way that suggests the partnership, or the European Commission endorses you or your use. You may not apply legal terms or technological measures that legally restrict others from using the material in the same manner that you did.

Copyright © DeCAIR Consortium, 2021-2024

Email: <u>DeCAIR@ju.edu.jo</u>

Project Website: http://DeCAIR.ju.edu.jo/





Course title	Al and Robotics Systems Lab		
Course number	0109576		
Credit hours	1		
ECTS (weekly contact and self-study load)	3		
Prerequisites/co-requisites	Robotics systems (0109563)		
Prerequisites by topic	Students are assumed to have good background in robotics systems, machine learning. Additionally, the students should have good programming skills.		
Level and type (compulsory, elective)	bachelor's compulsory course		
Year of study and semester	Fifth year, first semester		
Description	This course is a hands-on introduction to the key concepts of robotics and AI. Each student will use different types of robots and AI boards to learn about the general functioning of a robotics and AI systems.		
Objectives	To enable the students to have hands-on experience in the fields of artificial intelligence robotics.		
Intended learning outcomes	Upon successful completion of this course, students will be able to:		
	No	Intended learning Outcome (ILO)	Program learning outcome (PLO)*
	1	Understand different types of robotics systems and their applications	1
	2	Design and implement different functions for robotics systems (path planning, path smoothing, and vision)	1,2,5
	3	Design and implement several AI algorithms using PCs and GPU boards	2,5
	4	Understand how the AI is used to improve robotics systems	5,7
	(*) The PLOs are listed in the appendix		
Teaching and learning methods	Development of ILOs is promoted through the following teaching and learning methods:		
	 Experiments will be conducted in the lab The AI and Robot lab is open for the students to practice the practical aspects and solve the programming homework assignments. The student solves the programming assignments in machine learning and robotics. 		







	 The student carries out a term project for solving a problem using ML techniques. The student develops a professional report for each experiment. 					
		he student develops he student presents			ach experin	ient.
Learning material	Lab manual, Textbook, some instructor keynotes, selected YouTube videos, and			videos, and		
	access to a personal computer and the internet.					
Resources and references	A- Requi	A- Required book(s), assigned reading and audio-visuals:				
	1.	Robotics Lab Man	ual (Upon	installing the La	ab This Manu	ual will be
	2.	delivered) Artificial Intelligen will be delivered)	ice Lab Ma	inual (Upon inst	alling the La	b This Manual
Topic outline and schedule	Week		Tonic		110	Posourcos
	1	Intro to Robot (Mot	Topic		ILO 1	Resources 1
	2	•		and Color)	1,2	1
	3	Intro to Robot Vision (Depth and Color) Intro to Robot Vision (Depth and Color) Robot Navigation (path planning) Robot Navigation (localization) Programming robot Complex Behaviors Introduction to parallel computing Introduction to Al boards Supervised learning Supervised learning Unsupervised learning Deep neural networks Autonomous Robots Autonomous Robots			1,2	1
	4				2	1
	5			1)	2	1
	6				2	1
	7			3	2	
	8			3	2	
	9			3	2	
	10			3	2	
	11			3	2	
	12			3,4	2	
	13			3,4	1, 2	
	14			3,4	1, 2	
e al arta da la	15	Finals	1		1-4	1, 2
Evaluation tools	Opportunities to demonstrate achievement of the ILOs are provided throfollowing assessment tools:		through the			
	<u> </u>	Assessment tool	Mark	Торі	c(s)	Time
	Lab rep	orts	40%	Programming	aspects	W1-W14
	Midterr	Midterm exam		till supervised learning		W9
	Final ex	am	40%	All material		W15
	Total		100%			
Student requirements	The student should have a computer and internet connection.					
Lab policies		dance policies:				
		Attendance is required in inversity polices will				class and the



Developing Curricula for Artificial Intelligence and Robotics (DeCAIR) 618535-EPP-1-2020-1-JO-EPPKA2-CBHE-JP



	B- Absences from exams and submitting assignments on time:
	 A makeup exam can be arranged for students with acceptable absence causes. Assignments submitted late, but before announcing or discussing the solution can be accepted with 25% penalty. The project report must be handed in in time.
	C- Health and safety procedures:
	 All health and safety procedures of the university and the school should be followed.
	D- Honesty policy regarding cheating, plagiarism, misbehavior:
	 All submitted work must be of the submitting student. Other text or code must be properly quoted with clear source specification. Cheating will not be tolerated.
	E- Available university services that support achievement in the course:
	 Microsoft Teams team and Moodle course page Al Lab for practicing the practical aspects and solving the programming assignments. Program announcements Facebook group
Additional information	None





PLOs for the BSc in Intelligent Systems Engineering

Students who complete the BSc in Intelligent Systems Engineering (ISE) will be able to:

- 1. Identify, formulate, and solve complex engineering problems by applying principles of engineering, science, and mathematics.
- 2. Apply engineering design to produce solutions that meet specified needs with consideration of public health, safety, and welfare, as well as global, cultural, social, environmental, and economic factors.
- 3. Communicate effectively with a range of audiences.
- 4. Recognize ethical and professional responsibilities in engineering situations and make informed judgments, which must consider the impact of engineering solutions in global, economic, environmental, and societal contexts.
- 5. Function effectively on a team whose members together provide leadership, create a collaborative and inclusive environment, establish goals, plan tasks, and meet objectives.
- 6. Develop and conduct appropriate experimentation, analyze and interpret data, and use engineering judgment to draw conclusions.
- 7. Acquire and apply new knowledge as needed, using appropriate learning strategies.